

Unsupervised Machine Learning for the Quadratic Assignment Problem

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- 1 Introduction
 - The Quadratic Assignment Problem
 - Algorithms for the QAP
- 2 Machine Learning
 - Possible approaches
 - Extraction and Combination of Frequent Itemsets
- 3 Computational experiments
- 4 Conclusions
- 5 Announcement

The Quadratic Assignment Problem

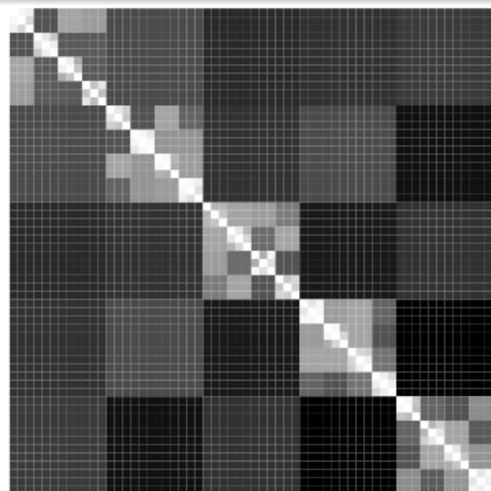
First description: [Koopmans and Beckmann(1957)], Monograph: [Çela(1998)]

Definition

- **Data:** Matrices $A = (a_{ij})$ (flows) and $B = (b_{ij})$ (distances), $n \times n$
- **Solution:** A permutation π of $\{1, 2, \dots, n\}$ (position) of the n items
- **Objective:** $\min_{\pi} z(\pi) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{\pi(i)\pi(j)}$



“Matrix dot product”



Algorithms for the QAP

- Exact algorithms: $n < 35, 49$
- Constructive algorithms (heuristics)
 - Greedy algorithms not efficient: placing the first item costs nothing; the cost of placing the last item can be arbitrarily large
 - Learning good positions for each item (Ant Systems)
 - Goal of this work: can we learn good positions with locally optimum solutions?
- Local searches
 - Taboo searches (Robust, Reactive)
 - Late Acceptance Hill Climbing
 - With Ant Systems: FANT
 - With Population Management: GA, Path Relinking

Machine Learning : Possible approaches

- Ideally: $2n^2$ inputs \rightarrow n outputs (a good permutation)
 - Far from supervised ML capabilities (even for simpler problems like TSP)

- Unsupervised learning
 - Clustering, k-means
 - Neural networks (various topologies, self-organizing (Kohonen) maps)
 - Principal component analysis
 - Frequent features (itemset) appearing in local optima

Extraction and Combination of Frequent Itemsets

Suppose we have 4 local optimum solutions

position	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>	...
	10	8	7	14	1	13	21	...
item	2	8	7	5	1	17	11	...
	10	11	7	13	1	14	24	...
	9	8	4	7	1	14	24	...

Supported itemsets (frequency > 25% for this portion):

1-itemset	2-itemset	3-itemset	4-itemset
1 - <i>e</i> (100%)	1 - <i>e</i> 7 - <i>c</i> (75%)	1 - <i>e</i> 7 - <i>c</i> 8 - <i>b</i> (50%)	none
7 - <i>c</i> (75%)	1 - <i>e</i> 8 - <i>b</i> (75%)	1 - <i>e</i> 7 - <i>c</i> 10 - <i>a</i> (50%)	
8 - <i>b</i> (75%)	1 - <i>e</i> 10 - <i>a</i> (50%)	1 - <i>e</i> 14 - <i>f</i> 24 - <i>g</i> (50%)	
10 - <i>a</i> (50%)	1 - <i>e</i> 14 - <i>f</i> (50%)		
14 - <i>f</i> (50%)	1 - <i>e</i> 24 - <i>g</i> (50%)		
24 - <i>g</i> (50%)	7 - <i>c</i> 8 - <i>b</i> (50%)		
	7 - <i>c</i> 10 - <i>a</i> (50%)		
	14 - <i>f</i> 24 - <i>g</i> (50%)		

Apriori algorithm for the extraction of frequent itemsets

Data: *solutions*, *min_sup* and *itemsets_limit*

Result: *all_itemsets*

```
1  $k \leftarrow 1$ 
2  $C_k \leftarrow \text{generate\_itemsets}(\text{solutions}, \emptyset, \emptyset)$ 
3  $L_k \leftarrow \text{filter\_itemsets}(C_k, \text{min\_sup}, \emptyset)$ 
4  $\text{all\_itemsets} \leftarrow L_k$ 
5 while  $L_k \neq \emptyset$  do
6    $C_{k+1} \leftarrow \text{generate\_itemsets}(\text{solutions}, L_k, L_1)$ 
7    $L_{k+1} \leftarrow \text{filter\_itemsets}(C_{k+1}, \text{min\_sup}, \text{itemsets\_limit})$ 
8    $\text{all\_itemsets} \leftarrow \text{all\_itemsets} \cup L_{k+1}$ 
9    $k \leftarrow k + 1$ 
0 end
```

Global algorithm for extraction and combination of frequent itemsets

Data: *instance_data* (Flow and distance matrices), *nb_solutions* (10,000), *nb_generations* (8), *min_sup* (0.1%) and *itemsets_limit* (1,000,000 for each *k*)

Result: *solutions*

```
1 forall  $i \leftarrow 1, \dots, nb\_solutions$  do
2   |  $solutions[i] \leftarrow random\_initialization()$ 
3   |  $solutions[i] \leftarrow local\_search(instance\_data, solutions[i])$ 
4 end
5 forall  $generation \leftarrow 1, \dots, nb\_generations$  do
6   |  $all\_itemsets \leftarrow extract\_itemsets(solutions, min\_sup, itemsets\_limit)$  (Apriori algorithm)
7   | forall  $i \leftarrow 1, \dots, nb\_solutions$  do
8     |  $solutions[i] \leftarrow combine\_itemsets(all\_itemsets)$ 
9     |  $solutions[i] \leftarrow local\_search(instance\_data, solutions[i])$ 
0   | end
1 end
```

Policies for combining itemsets

1 REFI Random exploration of all frequent itemsets

- All itemset that can validly complete a partial solution have the same probability of being chosen

2 ESFI

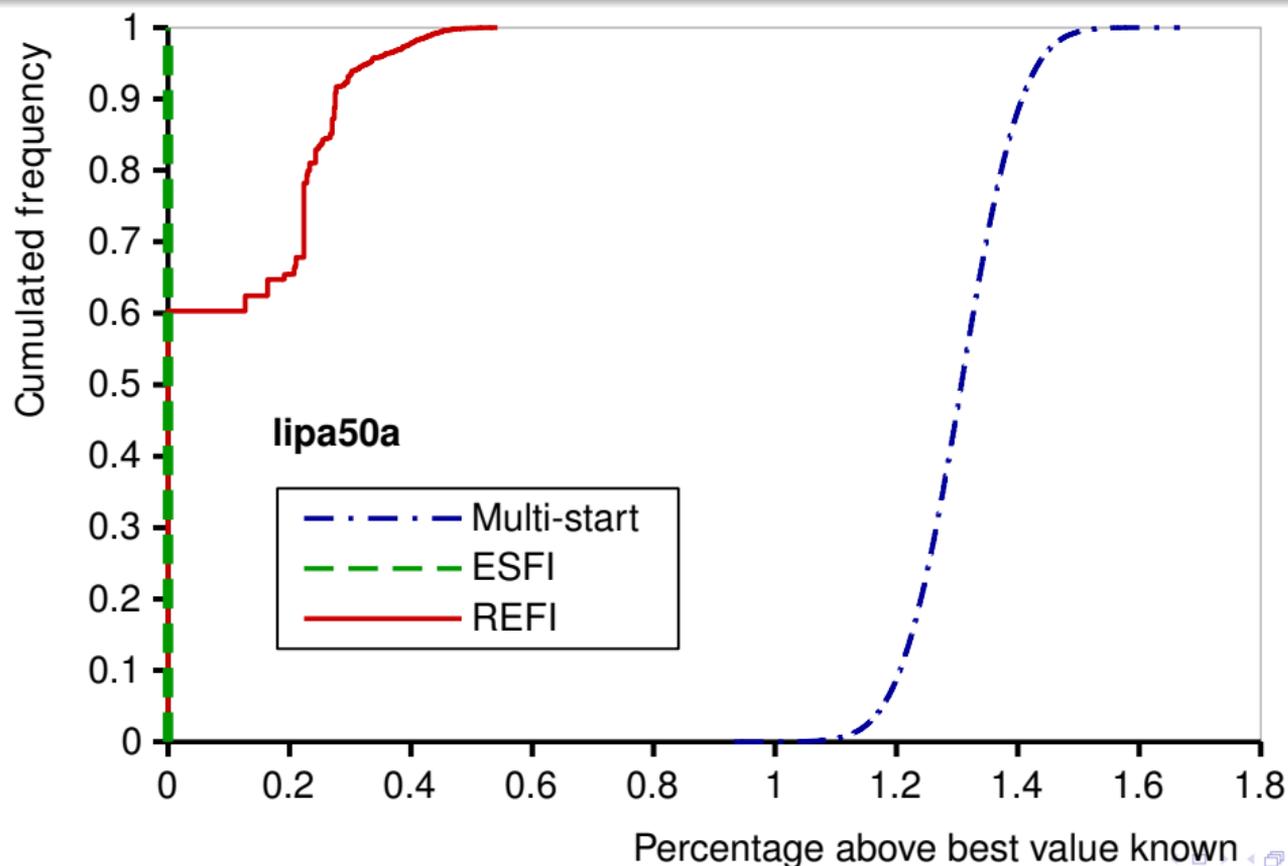
- An itemset has a probability proportional to its occurrence frequency of being chosen
 - Ant System use a similar construction mechanism: Pheromone trails corresponds to 1-itemsets
 - Tabu search exploits itemsets in the reverse way: 2-itemsets to forbid solutions characteristics, 1-itemsets to diversify the search
 - The cross-over operator in genetic algorithms extracts the largest itemset, then add 1-itemsets

In case a complete solution is not obtained: unassigned items are randomly added

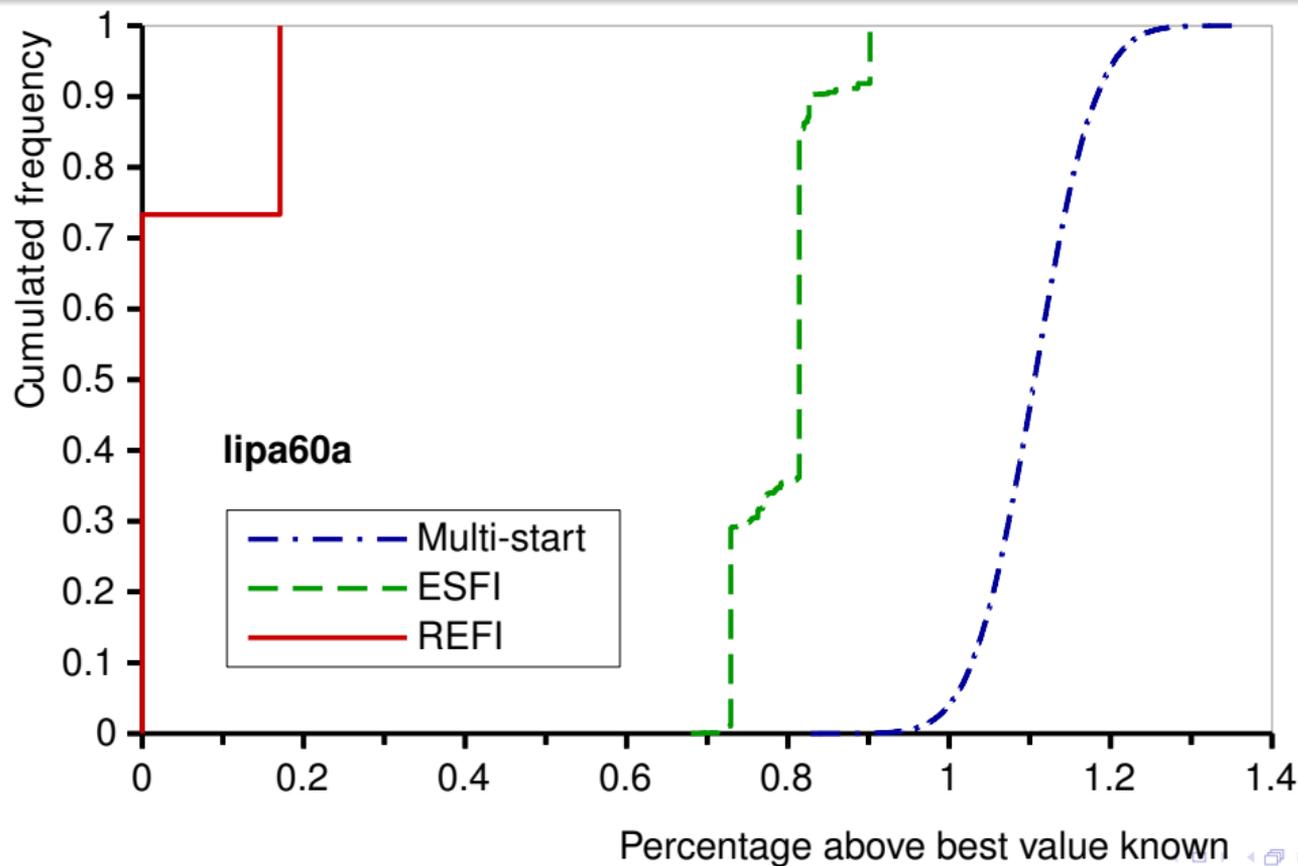
Computational experiments

- Computational time
 - Huge
 - About 1 day/generation for $n = 50$ on a CPU with 16 cores (32 threads)
 - The goal was not to design a horse race method
- Instances selection
 - Li and Pardalos : Special generation, known optimum (lipa..a, lipa..b) [Li and Pardalos(1992)]
 - Nugent-Skorin-Kapov : Grid distances, uniform flows (sko..) [Skorin-Kapov(1990)]
 - Symmetric, uniform distances and flows (tai..a) [Taillard(1991)]
 - Asymmetrical, non-uniformly generated (tai..b) [Taillard(1995)]
 - Grey patterns, high number of optimal solutions (tai..c) [Taillard(1995)]
 - Symmetrical and structured (tai..e) [Drezner et al.(2005)Drezner, Hahn, and Taillard]

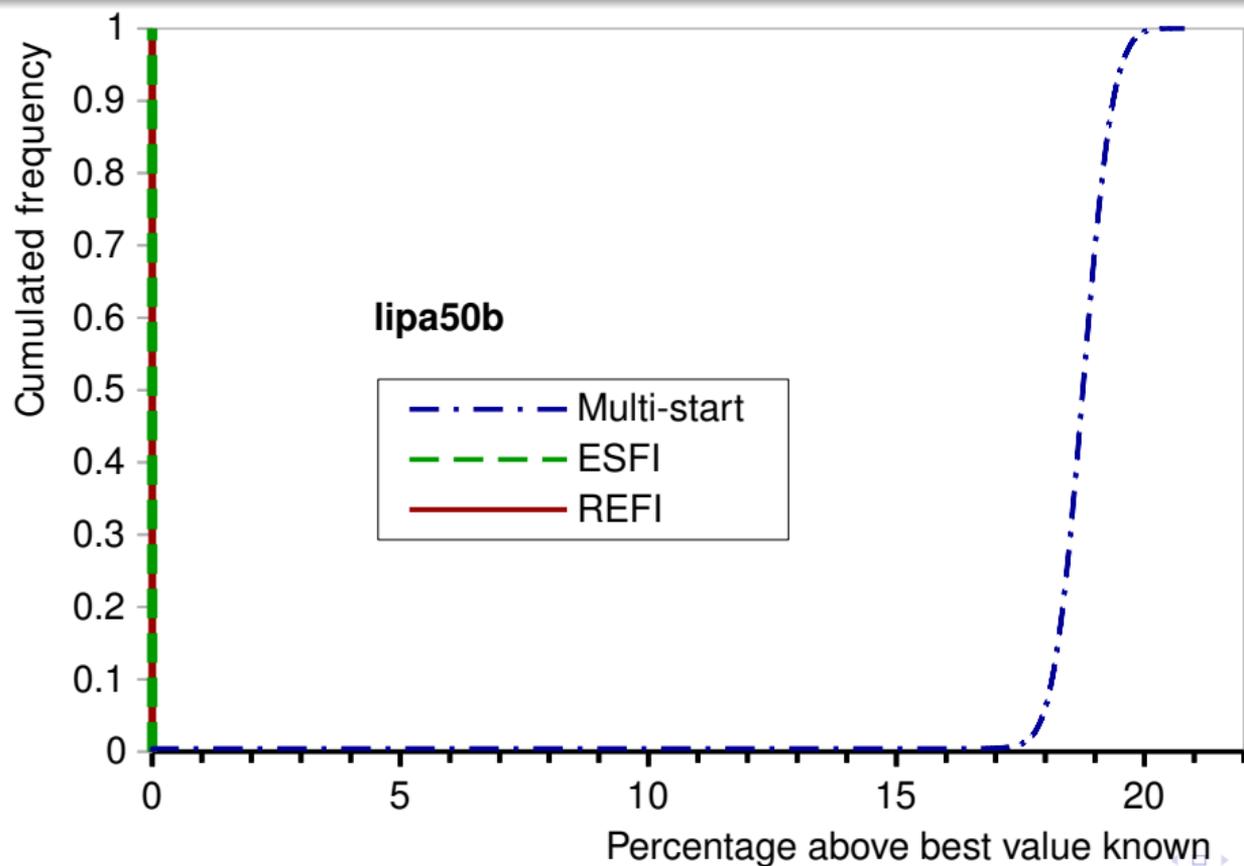
lipa50a



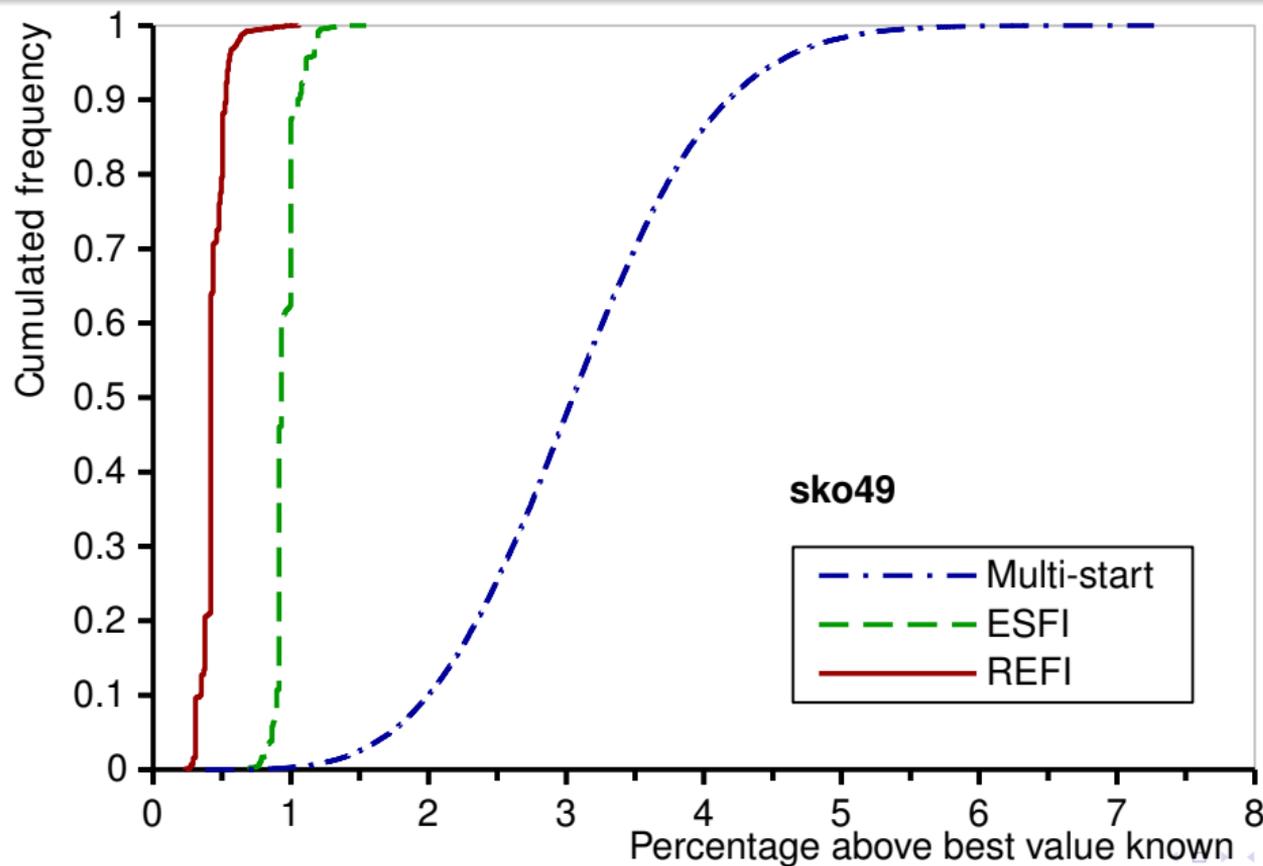
lipa60a



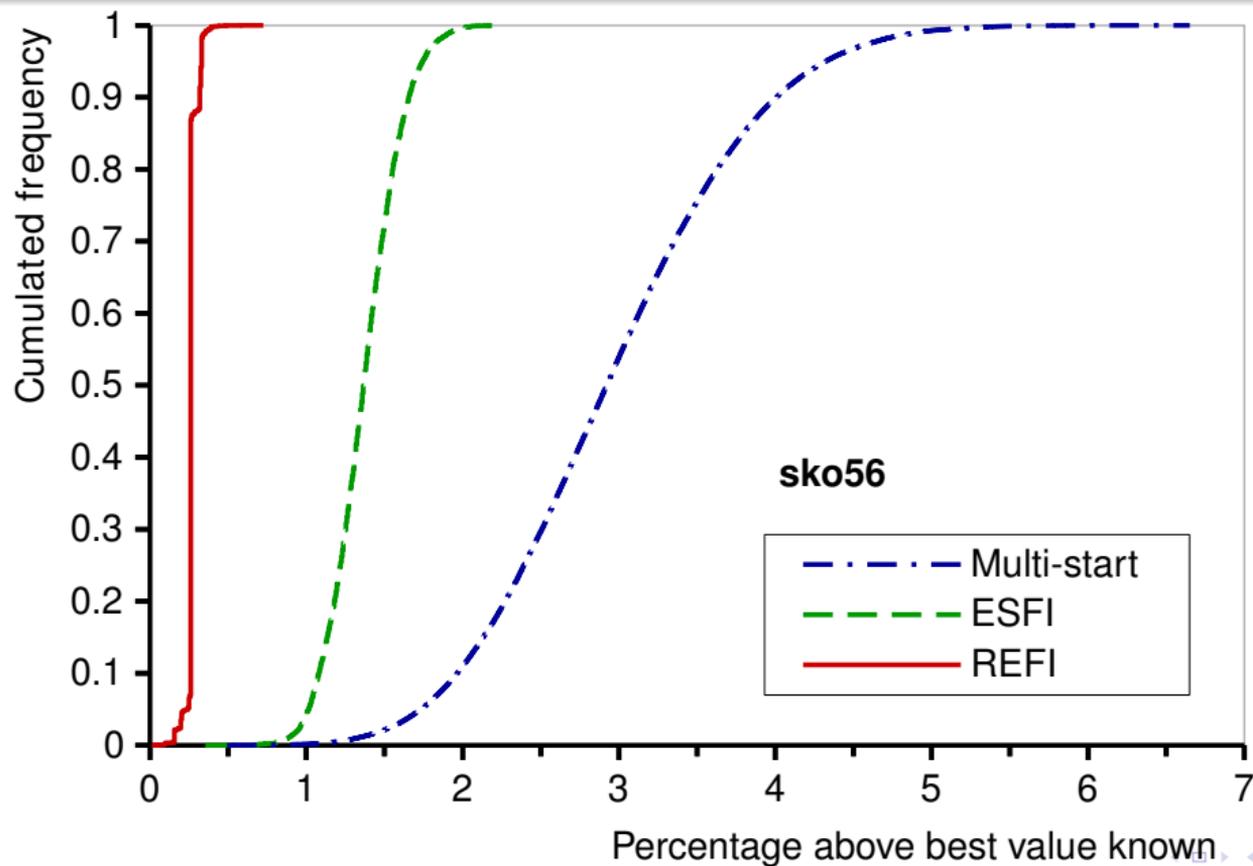
lipa50b



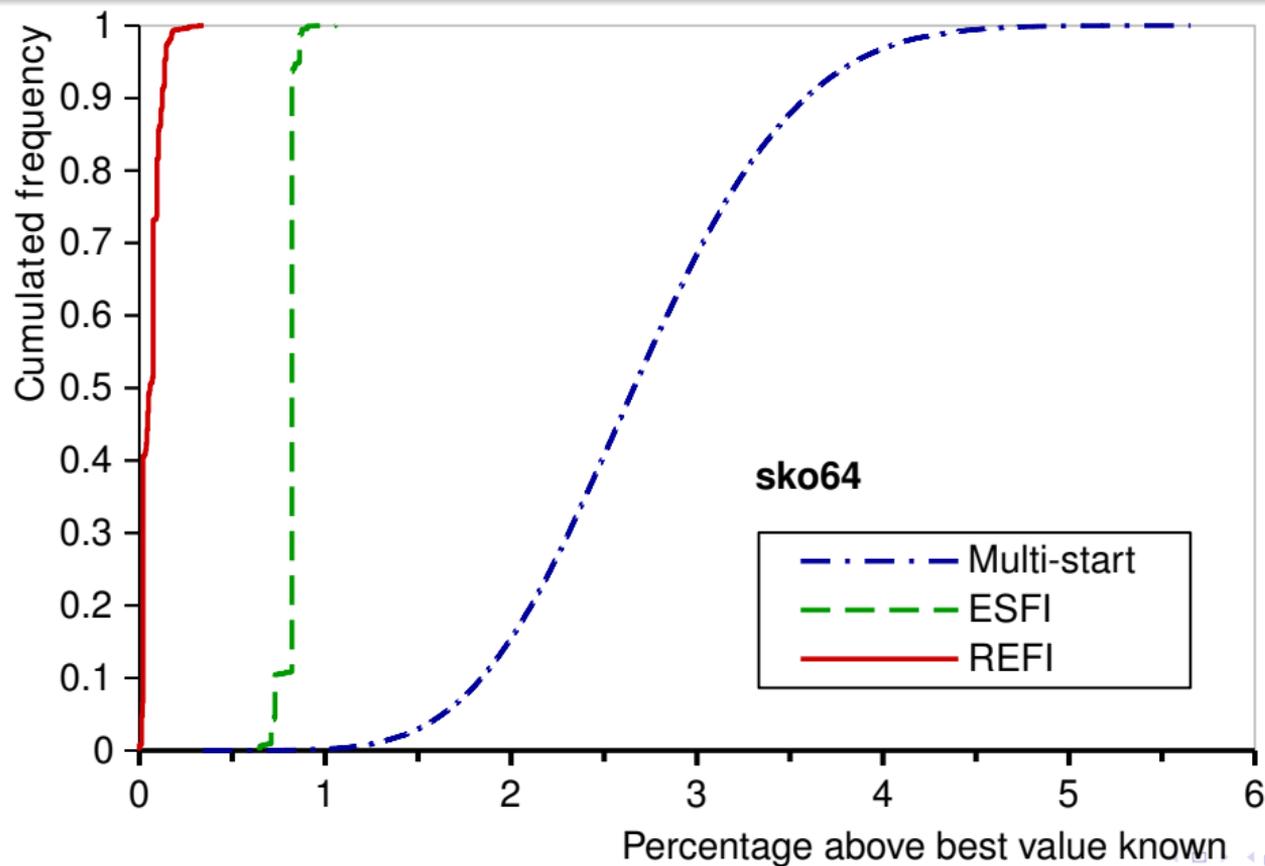
sko49



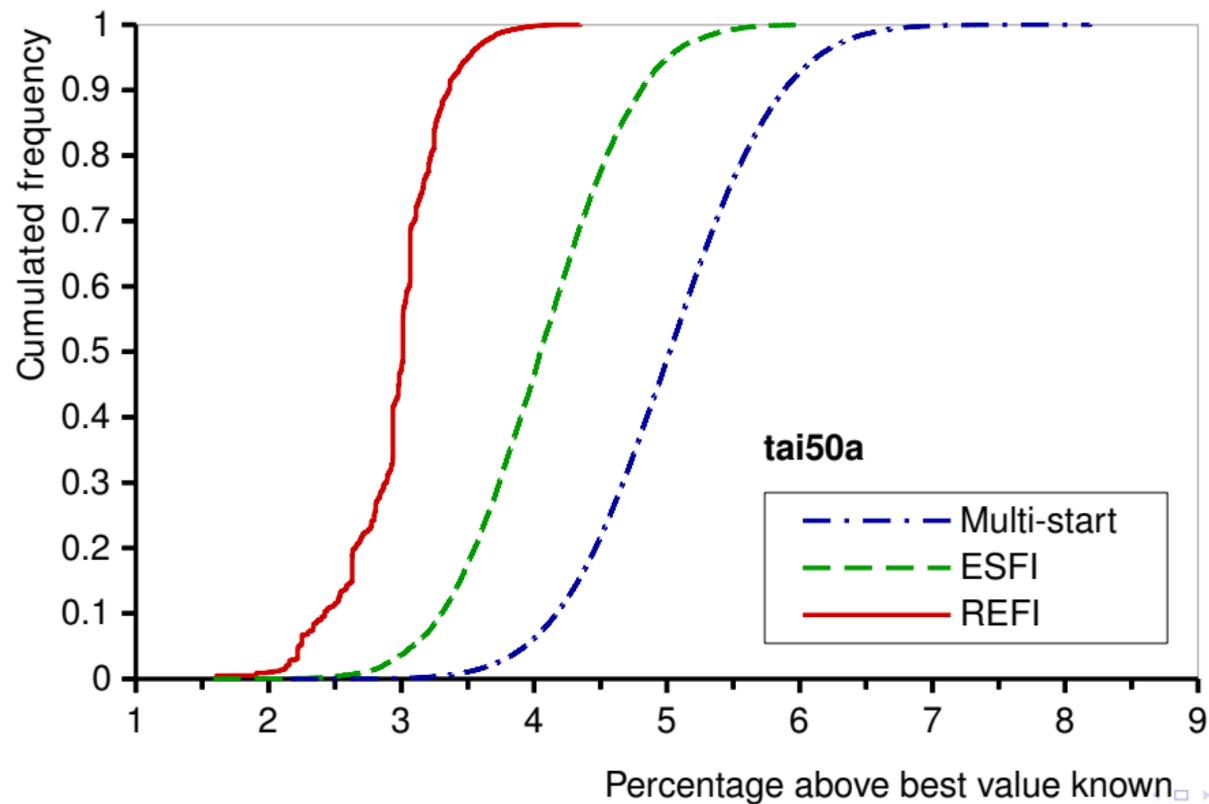
sko56



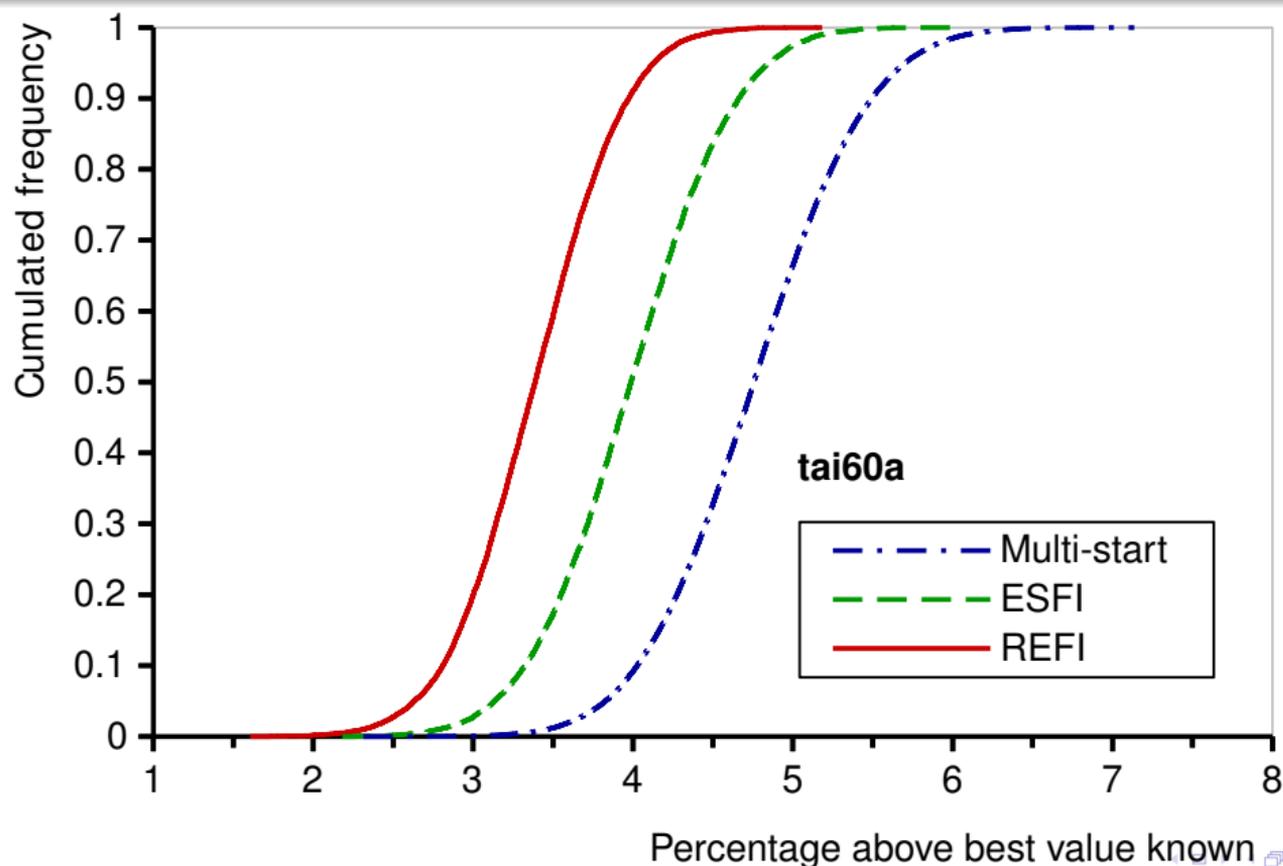
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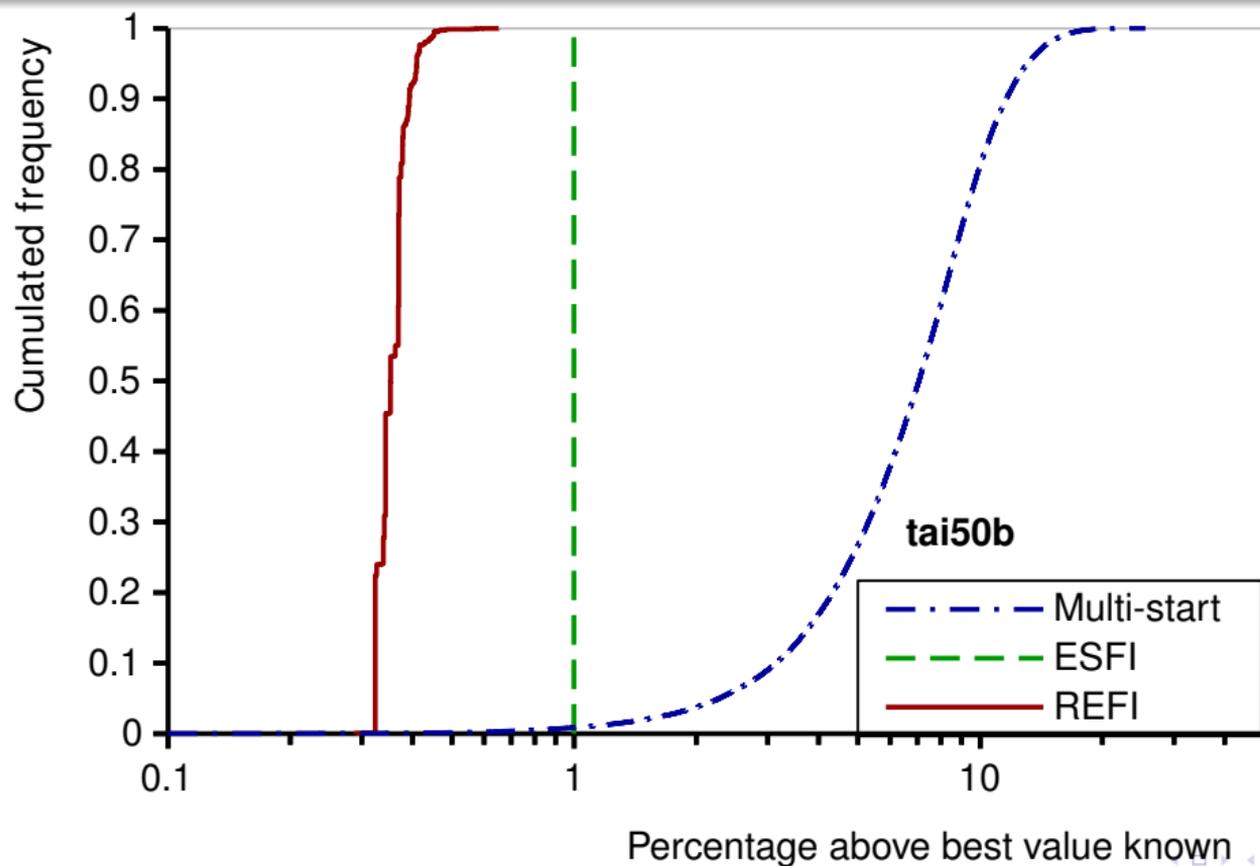
tai50a



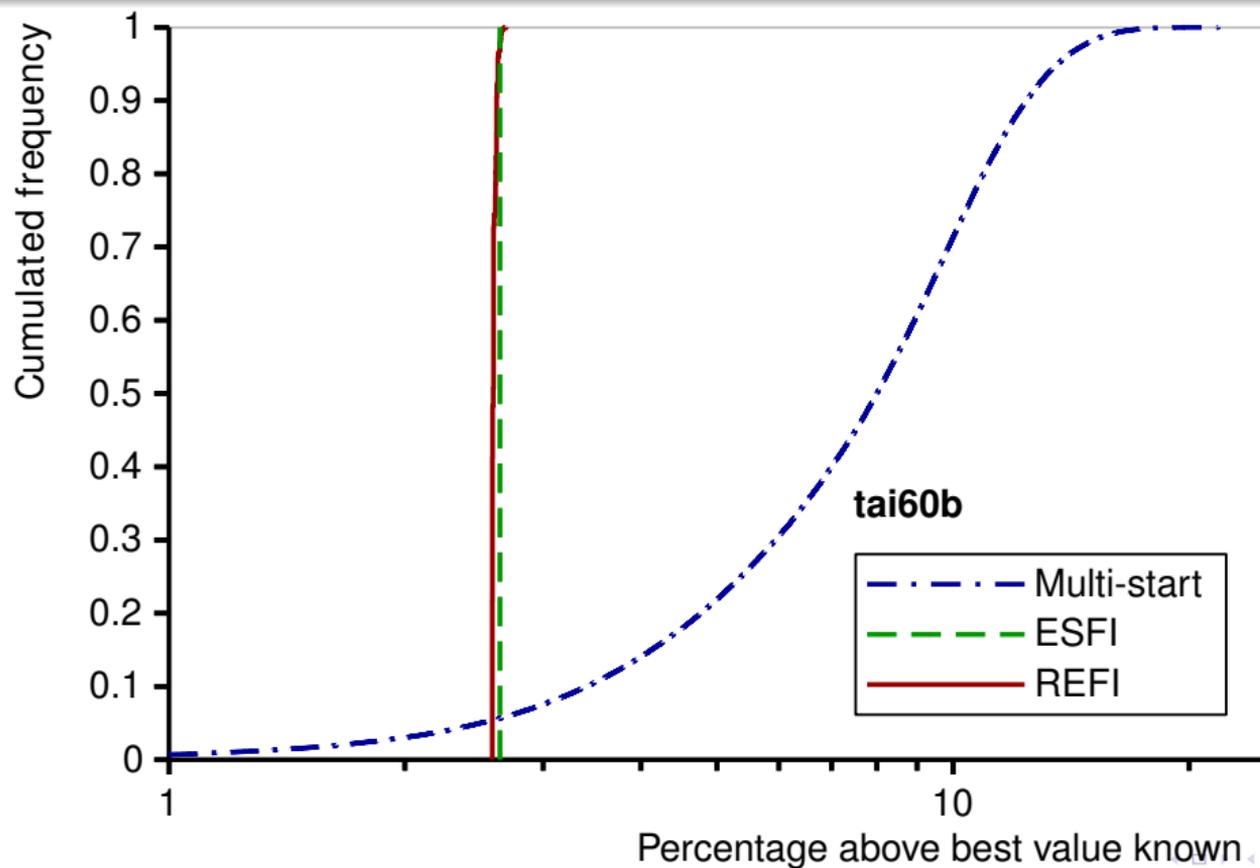
tai60a



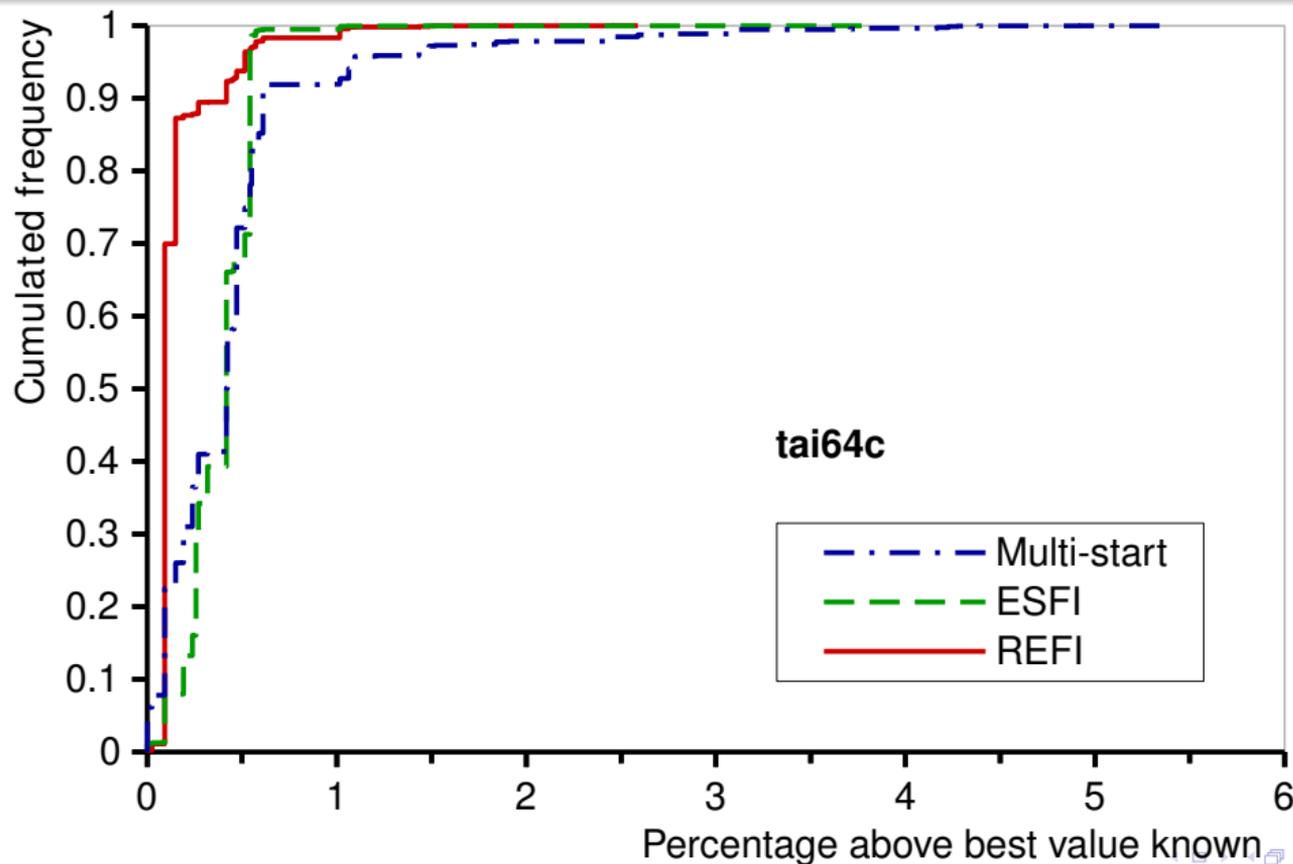
tai50b



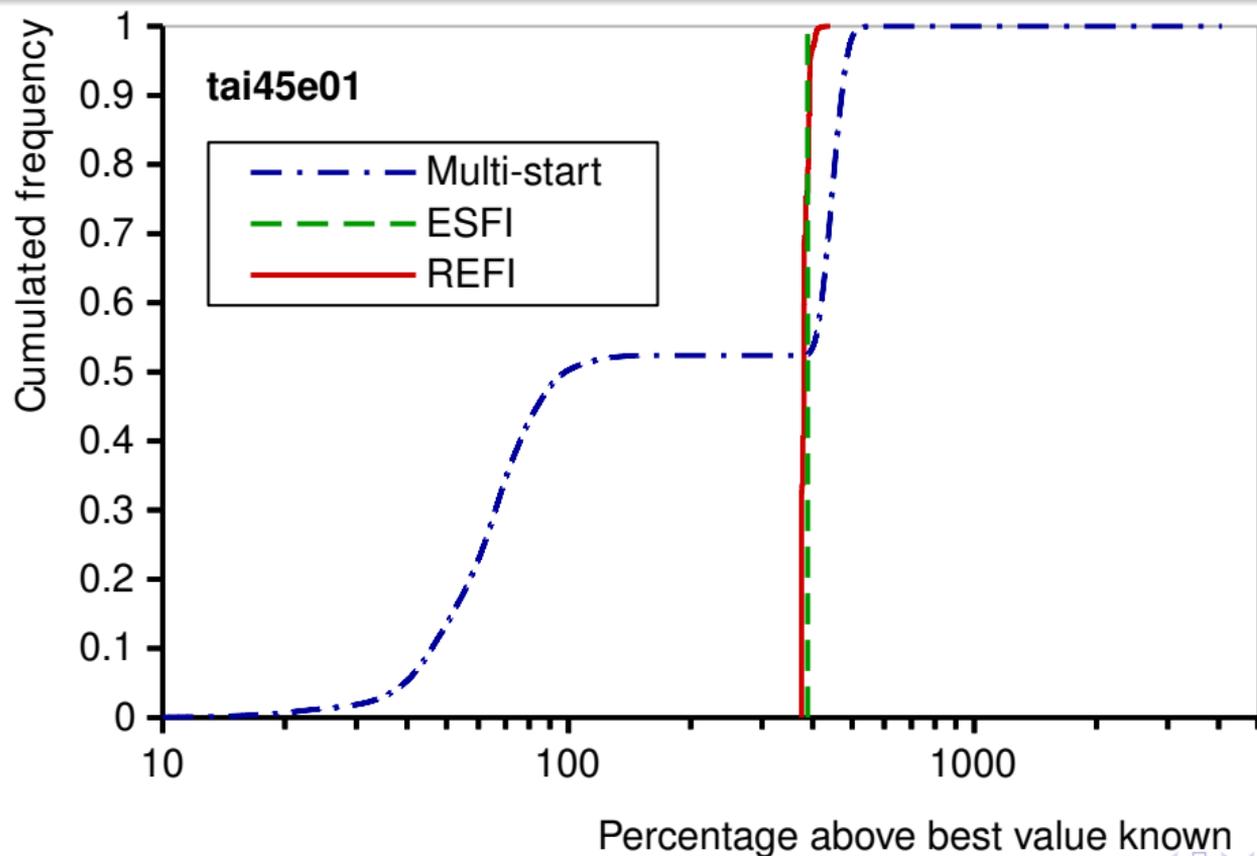
tai60b



tai64c



tai45e01



Conclusions

- Independent local searches can hardly find solutions less than 1% above optimum (excepted for tai..c instances)
- REFI is generally better than ESFI
- Building solutions with itemsets frequently found in local optima is efficient for limited instance types (lipa.., sko)
- Unsupervised learning can be highly inefficient for the QAP, even for structured instances
- This contrasts with other problems (for the TSP, a very high fraction of the edges of an optimal solution can be found by few dozen of moderately good solutions [Taillard(2022), Taillard and Heslgaun(2019)])
- A learning mechanism with the supervision of the objective function (as usually done in metaheuristics) is much more efficient. See, e.g. FANT [Taillard(1998)], Ro-TS [Taillard(1991)]

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